

MONARCH TRACTOR

How do we deploy autonomy safely?

3 layers of perception safety

- 360 Human safety with Object detection
- Semantic Segmentation
- Pointcloud obstacle detection

SW and HW integrity checks:

- Camera monitoring
- Failsafe SW design

Implement aware Autonomy

- Implement recognition pipeline
- Implement tracking & safety algorithm

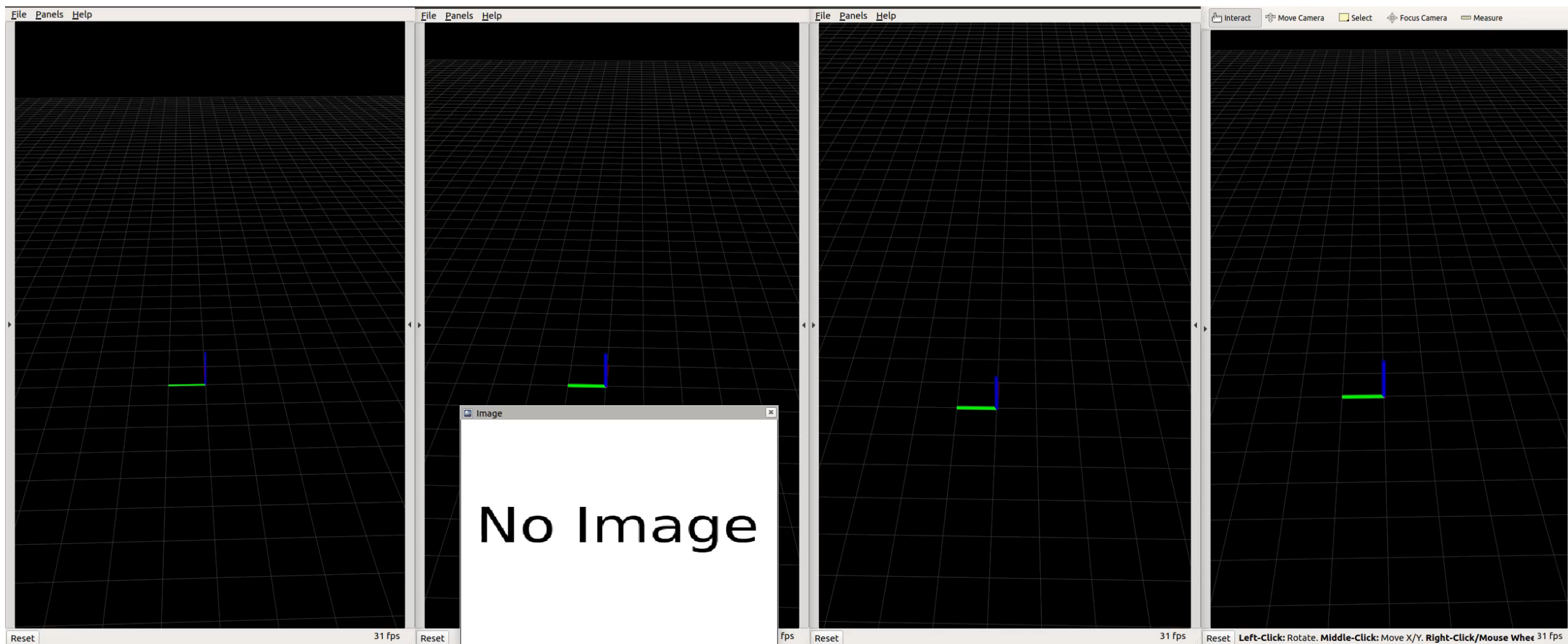
Human in the loop design

- App-based monitoring and review of safety triggers



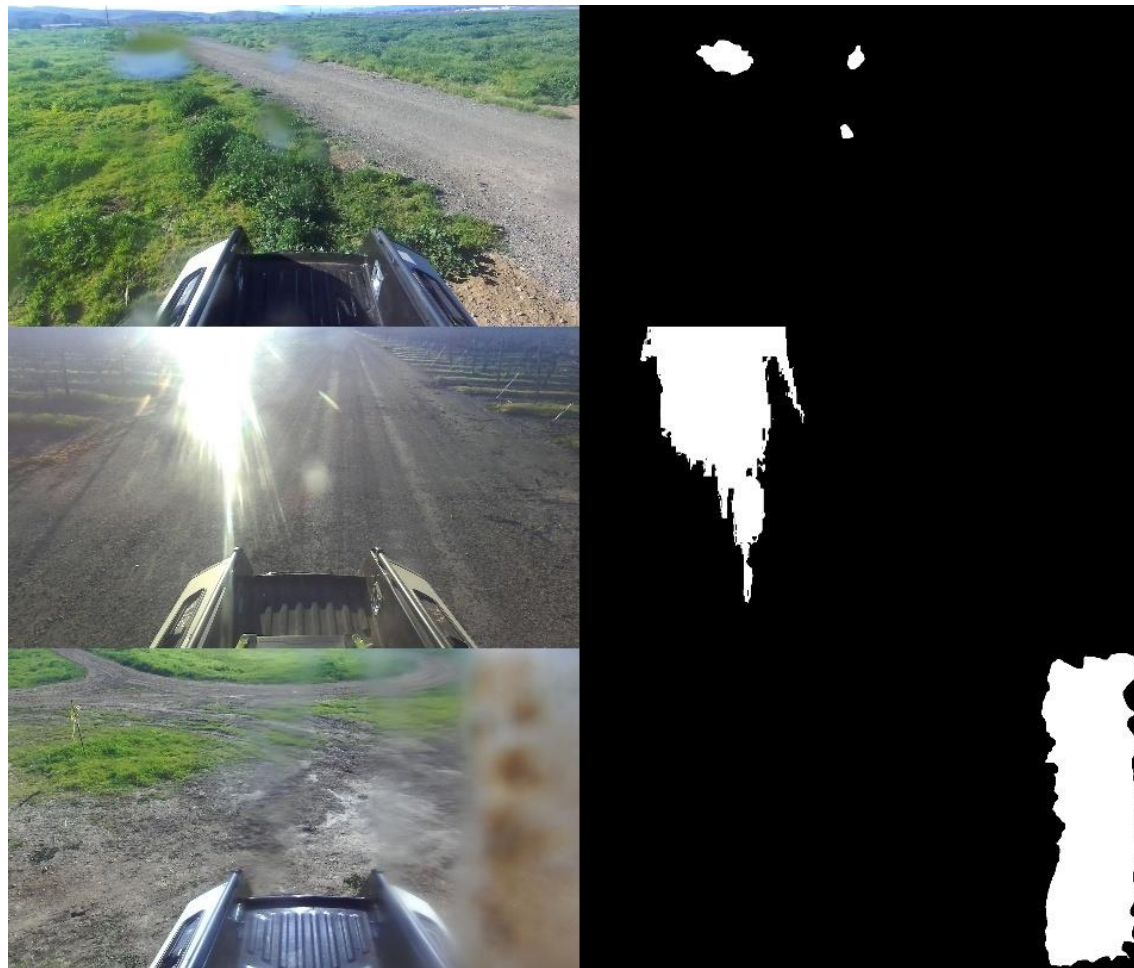
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Perception – 2D – Camera monitoring

- Detect various issues with camera such as:
 - Soiling
 - Blur
 - Glare
 - Obstruction





Implement Awareness Framework

- Challenge:
 - Hundreds of different farm implement models. Many are custom made.
 - Implements change the footprint and kinematics of the vehicle.
 - Farmers invested millions in farm implement fleets
- Goal:
 - Enable Monarch tractors to:
 - **Recognize** the implement make and model attached
 - **Track** the position of the implement for safety
 - **Monitor** the operation of the implement and detect faults
- Solution:
 - Implement Awareness Framework





Software enforced ODD restriction

- Geofencing
- Slope & speed restrictions

Implement certification process

- Only registered, recognizable and Autonomy certified implements
- Testing and Review process before certification

Phased deployment approach

- Phased approach from on-seat to off-seat with remote supervision.

Customer management

- Training materials
- Keep out policy
- Feature managed Autonomy

Autodrive: Autonomous Operations

